

# Project #4

## Runge-Kutta and Systems of ODEs

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The Idea: Given a system of ordinary differential equations with initial conditions, your program will solve the system and graph the system in a scene of the user's choosing.

The Details: Your program should accept the following items in one form or another:

- 1) The equations
- 2) The initial conditions
- 3) Initial start time  $t = a$
- 4) End stop time  $t = b$
- 5) The scene (which solution to plot versus which)

After you have the data in hand, your program must solve the system of ordinary differential equations using the Runge-Kutta Method of order 4. After the solution has been computed all the way to time  $t = b$ , the solution will be plotted in the scene selected by the user.

Remember that if you have the IVP  $y' = f(t, y)$ ,  $y(a) = y_a$ , then the scene is automatically just  $t$  vs.  $y(t)$ . However if you have the system  $y'_1 = f_1(t, y_1, y_2)$ ,  $y'_2 = f_2(t, y_1, y_2)$ ,  $y_1(a) = y_{1,a}$ ,  $y_2(a) = y_{2,a}$ , then you might wish to plot  $y_1(t)$  vs.  $y_2(t)$  for example.

Remarks: I suggest getting the simpler, one equation program working first. After completing that, modify the code for systems, and then finally do the plotting options.

Definitely take a look at all the sample codes in the book, they will help immensely!

Examples to test your code on:

1.

$$\begin{cases} y'_1 = -\frac{1}{2}y_1 + y_2 \\ y'_2 = -y_1 - \frac{1}{2}y_2 \\ y_1(0) = 1 \\ y_2(0) = 0 \\ t \in [0, 15] \end{cases}$$

with scenes  $t$  vs  $y_1(t)$  and  $y_1(t)$  vs.  $y_2(t)$ .

2.

$$\begin{cases} y'_1 = -\frac{5}{2}y_1 + y_2 + y_3 \\ y'_2 = y_1 - \frac{5}{2}y_2 + y_3 \\ y'_3 = y_1 + y_2 - \frac{5}{2}y_3 \\ y_1(0) = 2 \\ y_2(0) = 3 \\ y_3(0) = -1 \\ t \in [0, 15] \end{cases}$$

with scenes  $t$  vs  $y_3(t)$  and  $y_1(t)$  vs.  $y_2(t)$  and  $y_1(t)$  vs.  $y_3(t)$ .

3.

$$\begin{cases} y_1' = -2y_1 - y_2 + e^{-t} \\ y_2' = -3y_1 - 2y_2 - e^{-t} \\ y_1(0) = 1 \\ y_2(0) = 1 \\ t \in [0, 25] \end{cases}$$

with scenes  $t$  vs  $y_1(t)$  and  $y_1(t)$  vs.  $y_2(t)$ .